

Lyapunov methodology for stability analysis of impulsive systems

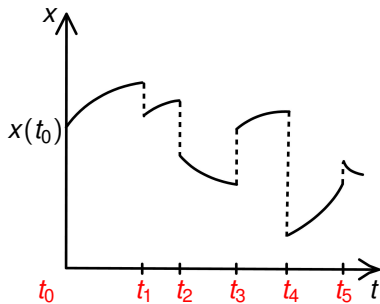
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Impulsive systems



$$\begin{aligned}\dot{x}(t) &= f(x(t), u(t)) & , t \notin \{t_1, t_2, \dots\}, \\ x(t) &= g(x^-(t), u^-(t)) & , t \in \{t_1, t_2, \dots\}.\end{aligned}$$

$u \in L_{\infty, loc}([t_0, \infty), \mathbb{R}^m)$, $x \in \mathbb{R}^n$ is abs. continuous between impulses,
 $x^-(t) := \lim_{s \nearrow t} x(s)$, $u^-(t) := \lim_{s \nearrow t} u(s)$.

ISS of impulsive system

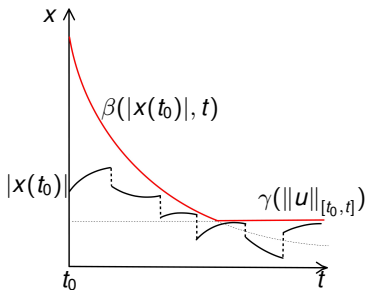
Definition (Input-to-state stability (ISS))

Σ is **ISS for a given impulse time sequence T** , if $\exists \beta \in \mathcal{KL}$ and $\gamma \in \mathcal{K}$, s.t.

$$|x(t)| \leq \max\{\beta(|x(t_0)|, t - t_0), \gamma(\|u\|_{[t_0, t]})\}$$

holds for all $x(t_0) \in \mathbb{R}^n$, $u \in L_{\infty, loc}([t_0, \infty), \mathbb{R}^m)$, $t \geq t_0$.

Σ is **uniformly ISS w.r.t. a class S of impulse time sequences**, if Σ is ISS $\forall T \in S$, and β and γ do not depend on the choice of $T \in S$.



ISS-Lyapunov functions (ISS-LF)

$$\Sigma : \begin{aligned} \dot{x}(t) &= f(x(t), u(t)), \quad t \neq t_k, \\ x(t) &= g(x^-(t), u^-(t)), \quad t = t_k, \quad k \in \mathbb{N}. \end{aligned}$$

Definition (ISS-Lyapunov function)

V is an **ISS-Lyapunov function** for Σ if $\exists \psi_1, \psi_2 \in \mathcal{K}_\infty$:

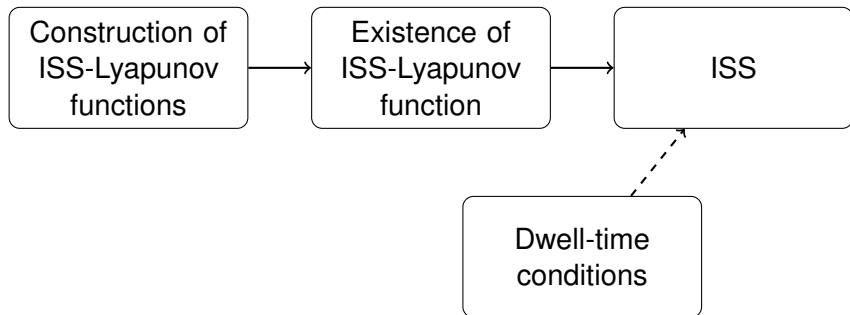
$$\psi_1(|x|) \leq V(x) \leq \psi_2(|x|), \quad x \in \mathbb{R}^n$$

and $\exists \gamma \in \mathcal{K}_\infty$, $\alpha \in \mathcal{P}$ and continuous function $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}$ with $\varphi(0) = 0$:

$$V(x) \geq \gamma(|u|) \Rightarrow \begin{cases} \nabla V(x) \cdot f(x, u) \leq -\varphi(V(x)), & \text{f.a.a. } x, u \\ V(g(x, u)) \leq \alpha(V(x)), & \forall x, u \end{cases}$$

If $\varphi(x) = cx$ and $\alpha(x) = e^{-d}x$, then V is an **exponential ISS-Lyapunov function**.

ISS-Theory for impulsive systems



Exponential ISS-Lyapunov functions

$$\Sigma : \begin{cases} \dot{x}(t) = f(x(t), u(t)), & t \neq t_k, \\ x(t) = g(x^-(t), u^-(t)), & t = t_k, \quad k \in \mathbb{N}. \end{cases}$$

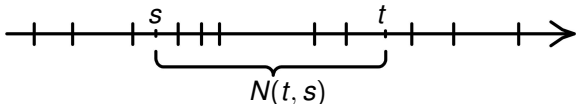
Definition

V is an **exponential** ISS-LF for Σ if $\exists \psi_1, \psi_2 \in \mathcal{K}_\infty$:

$$\psi_1(|x|) \leq V(x) \leq \psi_2(|x|), \quad x \in \mathbb{R}^n$$

and $\exists c, d \in \mathbb{R}$ and $\gamma \in \mathcal{K}_\infty$:

$$V(x) \geq \gamma(|u|) \Rightarrow \begin{cases} \nabla V(x) \cdot f(x, u) \leq -cV(x) \\ V(g(x, u)) \leq e^{-d}V(x). \end{cases}$$



$N(t, s)$ is the number of impulse times t_k in $(s, t]$.

Generalized ADT condition

Theorem (S.D., A.M., SICON 2013)

Let V be an exponential ISS-LF for Σ with coefficients $c, d \in \mathbb{R}$, $d \neq 0$.

$\forall h: \mathbb{R}_+ \rightarrow (0, \infty): \exists g \in \mathcal{L}: h(x) \leq g(x) \forall x \in \mathbb{R}_+$

$S[h]: \Leftrightarrow$ class of impulse time sequences:

$$-dN(t, s) - c(t - s) \leq \ln h(t - s) \quad \forall t \geq s \geq t_0. \quad (\text{gADT})$$

Then Σ is uniformly ISS w.r.t. $S[h]$.

Corollary (Hespanha, Liberzon, Teel 2008)

gADT with $h(x) = e^{\mu - \lambda x}$, $x \in \mathbb{R}_+$ \Rightarrow **ADT condition**.

ADT: $-dN(t, s) - (c - \lambda)(t - s) \leq \mu$, for any $s, t: 0 \leq s \leq t$.

ISS via **nonexponential** ISS-Lyapunov functions

We assume: **continuous dynamics is ISS** ($\varphi \in \mathcal{P}$)

$$V(x) \geq \gamma(\|u\|_U) \Rightarrow \begin{cases} \dot{V}_u(x) \leq -\varphi(V(x)) \\ V(g(x, u)) \leq \alpha(V(x)). \end{cases}$$

Let $S_\theta := \{\{t_i\}_1^\infty \subset [t_0, \infty) : t_{i+1} - t_i \geq \theta, \forall i \in \mathbb{N}\}$.

Theorem (S. Dashkovskiy, A.M., SICON, 2013)

Let V be ISS-Lyapunov function for Σ .

$$\exists \theta, \delta > 0 : \int_r^{\alpha(r)} \frac{ds}{\varphi(s)} \leq \theta - \delta, \quad \forall r > 0 \quad (\text{FDT})$$

\Rightarrow ISS \forall impulse time sequences $T \in S_\theta$.

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- ISS-Lyapunov functions
- Restrictions on the set of impulse time sequences

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What kind of restrictions do we need?

Overview of dwell-time conditions

for exponential LFs

generalized ADT

$$-dN(t, s) - c(t - s) \leq \ln h(t - s)$$

$$h(x) := e^{\mu - \lambda x}$$

Average DT

$$-dN(t, s) - (c - \lambda)(t - s) \leq \mu$$

$$\mu := -d$$

for nonexponential LFs

Fixed DT

$$\int_a^{\alpha(a)} \frac{ds}{\varphi(s)} \leq \theta - \delta$$

$$\varphi := c \cdot id$$

$$\alpha := e^{-d} \cdot id$$

$$\frac{1}{\theta} \leq \frac{c - \lambda}{-d}$$

ISS-Lyapunov functions for subsystems

$$\Sigma : \begin{cases} \dot{x}_i(t) = f_i(x_1(t), \dots, x_n(t), u(t)), & t \notin T, \\ x_i(t) = g_i(x_1^-(t), \dots, x_n^-(t), u^-(t)), & t \in T, \\ i = \overline{1, n}, \end{cases}$$

ISS-Lyapunov functions for subsystems

$$\Sigma : \begin{cases} \dot{x}_i(t) = f_i(x_1(t), \dots, x_n(t), u(t)), & t \notin T, \\ x_i(t) = g_i(x_1^-(t), \dots, x_n^-(t), u^-(t)), & t \in T, \\ i = \overline{1, n}, \end{cases}$$

$V_i : \mathbb{R}^{N_i} \rightarrow \mathbb{R}_+$ is an **ISS-Lyapunov function for i -th subsystem** of Σ if:

- 1 $\exists \psi_{i1}, \psi_{i2} \in \mathcal{K}_\infty$: $\psi_{i1}(|x_i|) \leq V_i(x_i) \leq \psi_{i2}(|x_i|)$, $\forall x_i \in \mathbb{R}^{N_i}$
- 2 There exist $\gamma_{ij}, \gamma_i \in \mathcal{K}$ and $\varphi_i \in \mathcal{P}$, so that

$$V_i(x_i) \geq \max\{\max_{j=1}^n \gamma_{ij}(V_j(x_j)), \gamma_i(|\xi|)\}$$

implies

$$\nabla V_i \cdot f_i(x, \xi) \leq -\varphi_i(V_i(x_i(t))).$$

- 3 There exist $\alpha_i \in \mathcal{P}$, such that

$$V_i(g_i(x, \xi)) \leq \max\{\alpha_i(V_i(x_i)), \max_{j=1}^n \gamma_{ij}(V_j(x_j)), \gamma_i(|\xi|)\}.$$

Small-gain theorem

Let $\Gamma_M = (\gamma_{ij})_{i,j=1,\dots,n}$, $\gamma_{ij} \in \mathcal{K}_\infty \cup \{0\}$ (gain matrix).

Let us introduce the **gain operator** $\Gamma : \mathbb{R}_+^n \rightarrow \mathbb{R}_+^n$ defined by

$$\Gamma(s) := \left(\max_{j=1}^n \gamma_{1j}(s_j), \dots, \max_{j=1}^n \gamma_{nj}(s_j) \right), \quad s \in \mathbb{R}_+^n.$$

Theorem (Small-gain theorem)

Let $\forall \Sigma_i \exists$ an ISS-Lyapunov function V_i with gains γ_{ij} . If the **small-gain condition**

$$\Gamma(s) \not\geq s, \quad \forall s \in \mathbb{R}_+^n \setminus \{0\},$$

holds, then Σ possesses an ISS-Lyapunov function, defined by

$$V(x) := \max_i \{\sigma_i^{-1}(V_i(x_i))\}.$$

Small-gain theorem for construction of eISS LFs

$$P := \{f : \mathbb{R}_+ \rightarrow \mathbb{R}_+ : \exists a \geq 0, b > 0 : f(s) = as^b \forall s \in \mathbb{R}_+\}$$

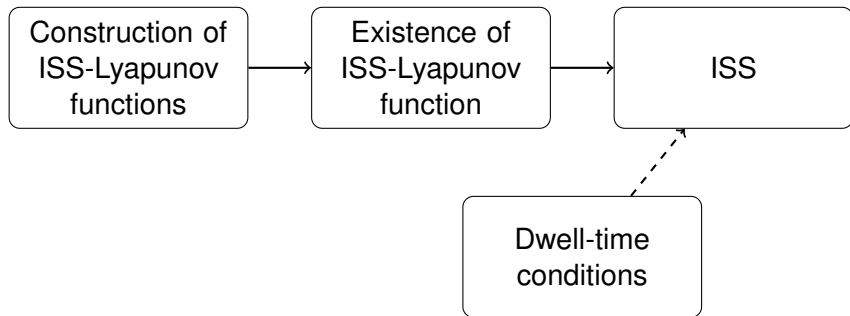
Theorem (SGT when subsystems have exponential ISS-LF)

Let V_i be *eISS Lyapunov function* for Σ_i with gains $\gamma_{ij} \in P$, $i = 1, \dots, n$, satisfying the small-gain condition. Then

$$V : x \mapsto \max_i \{\sigma_i^{-1}(V_i(x_i))\},$$

is an *eISS Lyapunov function* for Σ for *certain* σ .

E.g. $\sigma = Q(at)$, $a > 0$, $Q(x) := \text{MAX}\{x, \Gamma(x), \Gamma^2(x), \dots, \Gamma^{n-1}(x)\}$
(due to I. Karafyllis, Z.-P. Jiang (IMA Journal of Math. Cont. and Inf., 2011))



- Dwell-time conditions:
 - 1 nonlinear dwell-time conditions
 - 2 generalized average DT condition
- **Exponential** and **nonexponential** small-gain theorems.

The constructions work only if instabilities are matched!

Abstract ∞ -dim systems

$$\begin{aligned}\dot{x}(t) &= Ax(t) + f(x(t), u(t)) \quad , \quad t \notin \{t_1, t_2, \dots\}, \\ x(t) &= g(x^-(t), u^-(t)) \quad , \quad t \in \{t_1, t_2, \dots\}.\end{aligned}$$

- S. Dashkovskiy, A.M. Input-to-state stability of nonlinear impulsive systems, SICON, 2013.

Impulsive systems with time-delays

- S. Dashkovskiy, M. Kosmykov, A. Mironchenko, and L. Naujok. Stability of interconnected impulsive systems with and without time-delays using Lyapunov methods. Nonlinear Analysis: Hybrid Systems, 2012.

Hybrid systems

- Andrii Mironchenko, Guosong Yang and Daniel Liberzon. Lyapunov small-gain theorems for not necessarily ISS hybrid systems, submitted to MTNS 2014.